JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY KAKINADA
KAKINADA – 533 003, Andhra Pradesh, India
DEPARTMENT OF MECHANICAL ENGINEERING

I Year - II Semester		L	T	P	C
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ENIGINEERING MECHANICS					

Objectives: The students completing this course are expected to understand the concepts of forces and its resolution in different planes, resultant of force system, Forces acting on a body, their free body diagrams using graphical methods. They are required to understand the concepts of centre of gravity and moments of inertia and their application, Analysis of frames and trusses, different types of motion, friction and application of work - energy method.

UNIT – I
Objectives: The students are to be exposed to the concepts of force and friction, direction and itsapplication.

Introduction to Engg. Mechanics – Basic Concepts.
Systems of Forces: Coplanar Concurrent Forces – Components in Space – Resultant – Moment of Forceand its Application – Couples and Resultant of Force Systems.
Friction: Introduction**,** limiting friction and impending motion, coulomb's laws of dry friction,coefficient of friction, cone of friction

UNIT II
Objectives: The students are to be exposed to application of free body diagrams. Solution toproblems using graphical methods and law of triangle of forces.

Equilibrium of Systems of Forces: Free Body Diagrams, , Lami's Theorm, Equations of Equilibrium of Coplanar Systems, Graphical method for the equilibrium, Triangle law of forces, converse of the law of polygon of forces condition of equilibrium, Equations of Equilibrium for Spatial System of forces, Numerical examples on spatial system of forces using vector approach, Analysis of plane trusses.

UNIT – III
Objectives : The students are to be exposed to concepts of centre of gravity. The students are to be exposed to concepts of moment of inertia and polar moment of inertia including transfer methods and their applications.

Centroid: Centroids of simple figures (from basic principles) – Centroids of Composite Figures
Centre of Gravity: Centre of gravity of simple body (from basic principles), centre of gravity of composite bodies, Pappus theorems.
Area moments of Inertia: Definition – Polar Moment of Inertia, Transfer Theorem, Moments of Inertia of Composite Figures, Products of Inertia, Transfer Formula for Product of Inertia. **Mass Moment of Inertia:** Moment of Inertia of Masses, Transfer Formula for Mass Moments of Inertia, mass moment of inertia of composite bodies.

UNIT – IV
Objectives: The students are to be exposed to motion in straight line and in curvilinear paths, its velocity and acceleration computation and methods of representing plane motion.

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Rectilinear and Curvilinear motion of a particle: Kinematics and Kinetics- Work Energy method andapplications to particle motion- Impulse momentum method.

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UNIT – V

Objectives: The students are to be exposed to rigid motion kinematics and kinetics
Rigid body Motion: Kinematics and kinetics of translation, Rotation about fixed axis and plane motion, Work Energy method and Impulse momentum method.

TEXT BOOK:

1. Engg. Mechanics - S.Timoshenko & D.H.Young., 4th Edn - , Mc Graw Hill publications.

Course outcomes:

1. The student should be able to draw free body diagrams for FBDs for particles and rigid bodies in plane and space and problems to solve the unknown forces, orientations and geometric parameters.
2. He should be able to determine centroid for lines, areas and center of gravity for volumes and their composites.
3. He should be able to determine area and mass movement of inertia for composite sections
4. He should be able to analyze motion of particles and rigid bodies and apply theprinciples of motion, work energy and impulse – momentum.